

# Detecting blockages in water supply networks using boundary control

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Silvia Meniconi and Bruno Brunone's group

Inverse Days 2019

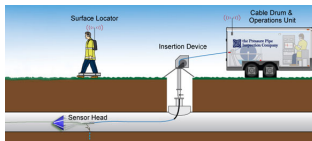
Jyväskylä,  
December 17, 2019

# Water supply network



# How to locate problems traditionally?

## Sahara System



## Replace & Rehabilitate



## Sonar



## Gas Injection



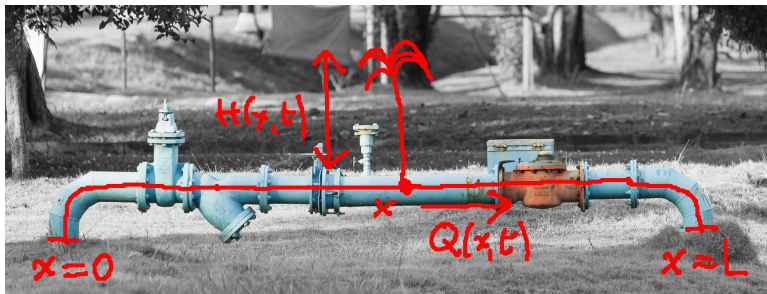
## Smart Ball



## Direct model: single pipe



## Direct model: single pipe



$$\partial_t H + \frac{a^2}{gA} \partial Q = 0, \quad 0 < x < L, \quad t \in \mathbb{R},$$

$$\partial_t Q + gA \partial H = 0, \quad 0 < x < L, \quad t \in \mathbb{R},$$

$$H = Q = 0, \quad 0 < x < L, \quad t \leq 0.$$

# One pipe inverse problem

Measurement  $\Lambda(t)$  defined by assuming  $H, Q$  satisfy

$$\begin{aligned}\partial_t H + \frac{a^2}{gA} \partial Q &= 0, & 0 < x < L, & \quad t \in \mathbb{R}, \\ \partial_t Q + gA \partial H &= 0, & 0 < x < L, & \quad t \in \mathbb{R}, \\ H = Q &= 0, & 0 < x < L, & \quad t \leq 0\end{aligned}$$

Boundary conditions:

unknown at  $x = L$

unit impulse discharge  $Q(0, t) = \delta_0(t)$  at  $x = 0$

Then  $\Lambda(t) = H(0, t)$ .

Recover:  $A(x)$  (or  $a(x)$ , or  $A(x)/a(x)$ )

## Integration by parts

For simplicity assume  $a(x) = a_0$  constant! Assume  $H, Q$  causal.  
Then

$$\partial_t H + \frac{a_0^2}{gA} \partial Q = 0$$

and integrate  $\int_0^\tau \int_0^{a_0\tau} \dots dx dt$  given any fixed  $\tau > 0$ .

$$- \int_0^\tau \int_0^{a_0\tau} \partial Q(x, t) dx dt = \int_0^\tau \int_0^{a_0\tau} \frac{gA(x)}{a_0^2} \partial_t H(x, t) dx dt$$

- ▶  $H = Q = 0$  at  $t = 0$
- ▶ hence  $H(x, t) = Q(x, t) = 0$  when  $x \geq a_0 t$ , so

$$\int_0^\tau Q(0, t) dt = \int_0^{a_0\tau} \frac{gA(x)}{a_0^2} H(x, \tau) dx \quad (1)$$

## Special solutions

Given causal solutions  $H, Q$  we know from boundary measurements the value of

$$V(\tau) := \int_0^\tau Q(0, t) dt = \int_0^{a_0\tau} \frac{gA(x)}{a_0^2} H(x, \tau) dx.$$

If  $H$  such that

$$H(x, \tau) = \begin{cases} 1, & x < a_0\tau \\ 0, & x \geq a_0\tau \end{cases} \quad \text{at } t = \tau,$$

then

$$A(x) = \frac{a_0}{g} (\partial V) \left( \frac{x}{a_0} \right)$$



## Unique continuation

If  $\mathcal{H}, \mathcal{Q}$  satisfy the equations on  $0 < x < L$ ,  $0 < t < 2\tau$  (but are not necessarily causal), and

$$\mathcal{H}(0, t) = 2, \quad \mathcal{Q}(0, t) = 0, \quad 0 < t < 2\tau,$$

then  $\mathcal{H}(x, t) = 2$ ,  $\mathcal{Q}(x, t) = 0$  in  $x < a_0(\tau - |\tau - t|)$ .

If

$$\mathcal{H}(x, t) = H(x, t) + H(x, 2\tau - t), \quad \mathcal{Q}(x, t) = Q(x, t) - Q(x, 2\tau - t)$$

where  $H, Q$  causal solutions, AND  $\mathcal{H}, \mathcal{Q}$  satisfy the above, then

$$2H(x, \tau) = \mathcal{H}(x, \tau) = \begin{cases} 2, & x < a_0\tau \\ 0, & x \geq a_0\tau \end{cases}$$

and so  $A(a_0\tau) = a_0 g^{-1} \partial_\tau \int_0^\tau Q(0, t) dt$ . ( $Q$  depends on  $\tau$ !!)

## Integral equation from requirements of $\mathcal{H}$ , $\mathcal{Q}$

Measurement (if  $A$  constant near  $x = 0$ ):

$$\Lambda(t) = \frac{a_0}{gA(0)}(\delta_0(t) + h(t))$$

Let  $H, Q$  be causal solutions such that  $\mathcal{H}(0, t) = 2$ ,  $\mathcal{Q}(0, t) = 0$  on  $0 < t < 2\tau$ . Then

$$Q(0, t) + \frac{1}{2} \int_0^{2\tau} Q(0, s) h(|s - t|) ds = \frac{gA(0)}{a_0}, \quad 0 < t < 2\tau.$$

Conversely, if  $Q$  solves the above and  $H$  is the corresponding pressure head, then

$$H(x, \tau) = \begin{cases} 1, & x < a_0\tau \\ 0, & x \geq a_0\tau \end{cases} \quad \text{at } t = \tau,$$

$$\text{so } A(a_0\tau) = a_0 g^{-1} \partial_\tau \int_0^\tau Q(0, t) dt$$

## Algorithm (SKIP?)

1. input  $Q(0, t) = \delta_0(t)$  and measure  $\Lambda(t) = H(0, t)$  for  $t < 2T = 2L/a_0$
2. for  $0 < \tau < T$  solve

$$Q(0, t) + \frac{1}{2} \int_0^{2\tau} Q(0, s) h(|s - t|) ds = \frac{gA(0)}{a_0}, \quad 0 < t < 2\tau$$

3. set

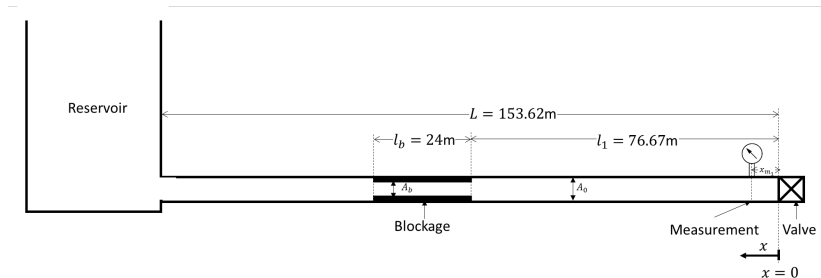
$$V(\tau) = \int_0^\tau Q(0, t) dt \quad \left( = \int_0^{a_0\tau} \frac{gA(x)}{a_0^2} dx \right)$$

4. repeat 2–3 (in the computer) for many  $\tau$  to get a good approximation of  $V(\tau)$
5. given  $x < L$  the area can be found by

$$A(x) = \frac{a_0}{g} \left( \frac{\partial}{\partial \tau} V(\tau) \right)_{\tau=x/a_0}$$

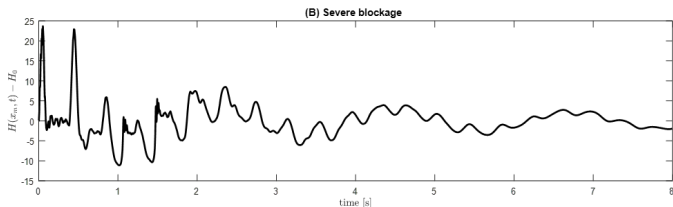
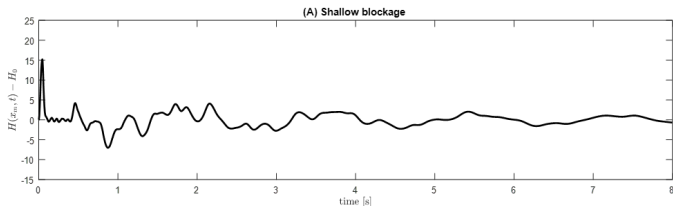
# Laboratory experiment: setup

Measurement set up by Silvia Meniconi and Bruno Brunone's group.



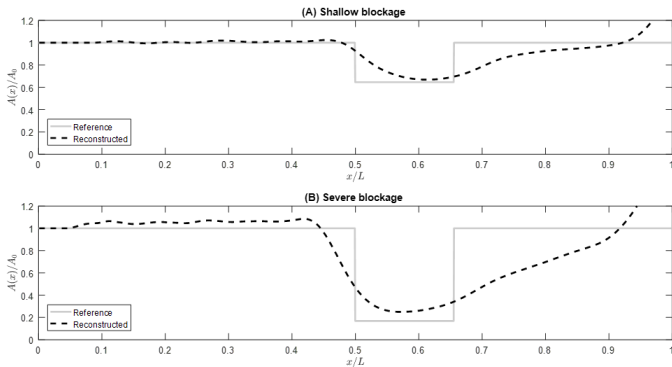
# Laboratory experiment: impulse-response function

Measurement set up by Silvia Meniconi and Bruno Brunone's group.

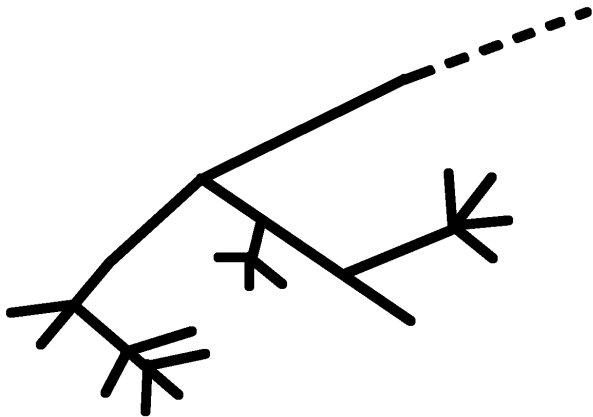


# Reconstruction from measured and processed data

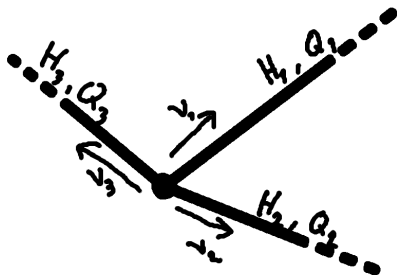
Measurement set up by Silvia Meniconi and Bruno Brunone's group.



# Network



## Junction conditions



- ▶  $H$  is a scalar: the boundary values  $H_j$  are the same at connected pipe ends
- ▶ No sinks or sources (total water flowing into pipes sum to zero):

$$\sum_j \nu_j Q_j = 0$$



## Integration by parts

Integrate one of the equations over a time-interval  $0 < t < \tau$  and the whole network  $x \in \mathbb{G}$ . This gives

$$\sum_{x_j \in \partial \mathbb{G}} \int_0^\tau \nu(x_j) Q(x_j, t) dt = \int_{\mathbb{G}} \frac{gA(x)}{a_0^2} H(x, \tau) dx$$

if  $H(x, t) = 0$  for  $t \leq 0$ .

Let  $\Omega \subset \mathbb{G}$ . If there are boundary flows  $Q(x_j, t)$  so that

$$H(x, \tau) = \begin{cases} 1, & x \in \Omega, \\ 0, & x \notin \Omega, \end{cases} \quad \text{at time } t = \tau.$$

Then we have

$$V(\Omega) := \sum_{x_j \in \partial \mathbb{G}} \int_0^\tau \nu(x_j) Q(x_j, t) dt = \frac{g}{a_0^2} \int_{\Omega} A(x) dx.$$

In which  $\Omega$  can we force  $H(x, \tau) = 1$ ?

Control theory suggests that there are boundary values such that  $H(x, \tau) = \chi_{\Omega}(x)$  given any measurable set  $\Omega \subset \mathbb{G}$  when  $\mathbb{G}$  is a tree.

In which  $\Omega$  can we force  $H(x, \tau) = 1$ ?

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HOWEVER

Can we solve for these boundary values? Is it computationally efficient? Is it even possible?

## Use the one pipe method

What if we set  $\mathcal{H}(x_j, t) = 2$ ,  $\mathcal{Q}(x_j, t) = 0$  on boundary points  $x_j \in \partial\mathbb{G}$  for some time-intervals  $\tau - f(x_j) < t < \tau + f(x_j)$ ?

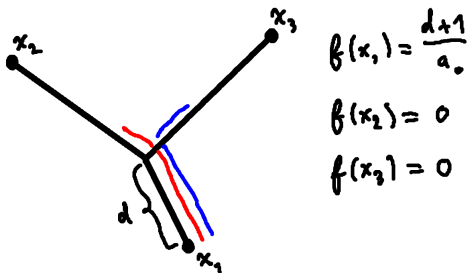
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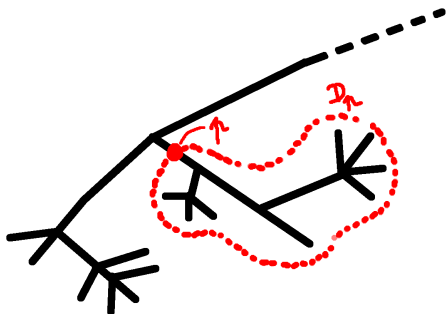
Unique continuation does NOT guarantee that  $\mathcal{H}(x, \tau) = 2$  in the *domain of influence*

$$\{x \in \mathbb{G} \mid d(x, x_j) < a_0 f(x_j) \text{ for some } x_j \in \partial\mathbb{G}\}.$$

For example:



## Admissible domains



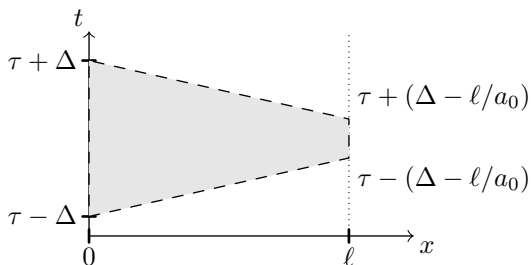
If  $p \in \mathbb{G}$  and

$$f(x_j) = \begin{cases} d(x_j, p)/a_0, & x_j \in \partial D_p \cap \partial \mathbb{G}, \\ 0, & x_j \in \partial \mathbb{G} \setminus \partial D_p. \end{cases}$$

then

$$D_p = \{x \in \mathbb{G} \mid d(x, x_j) < a_0 f(x_j) \text{ for some } x_j \in \partial \mathbb{G}\}.$$

# Inductive unique continuation



+ junction conditions  
= propagate  $\mathcal{H} = 2$ ,  $\mathcal{Q} = 0$ !!

If  $\mathcal{H}$ ,  $\mathcal{Q}$  satisfy the equations on  $x \in \mathbb{G}$ ,  $t \in \mathbb{R}$  (but are not necessarily causal), and

$$\mathcal{H}(x_j, t) = 2, \quad \mathcal{Q}(x_j, t) = 0, \quad x_j \in \partial\mathbb{G}, \tau - f(x_j) < t < \tau + f(x_j),$$

then  $\mathcal{H}(x, \tau) = 2$ ,  $\mathcal{Q}(x, \tau) = 0$  in  $D_p$  at  $t = \tau$ .

## Network integral equation

Let  $Q_p(x_j, t)$  satisfy ( $x_0$  is end to which we do not have access)

$$\begin{aligned} \frac{gA(x_j)}{a_0} &= \nu(x_j)Q_p(x_j, t) \\ &+ \sum_{\substack{x_i \in \partial\mathbb{G} \\ x_i \neq x_0}} \frac{\nu(x_i)}{2} \int_0^\tau Q_p(s, x_i) (h_{ij}(|t-s|) + h_{ij}(2\tau - t - s)) ds \end{aligned}$$

when  $\tau - f(x_j) < t \leq \tau$  and

$$Q_p(x_j, t) = 0$$

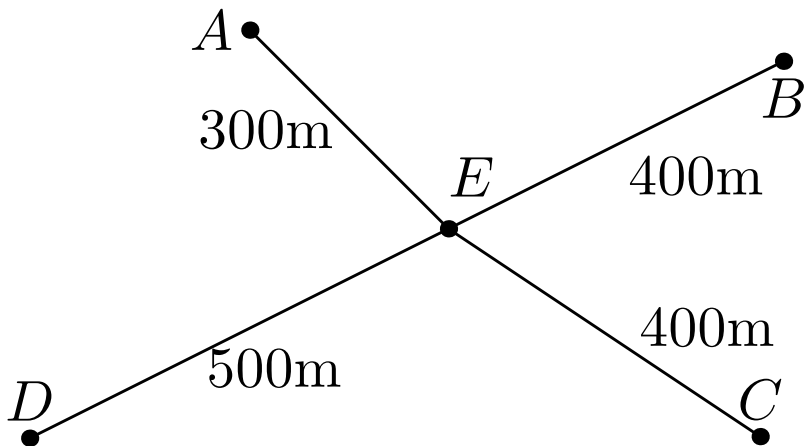
when  $0 \leq t \leq \tau - f(x_j)$ .

Then if  $H, Q$  satisfy the network wave model with boundary flow  $\nu Q_p$  we have

$$H(x, \tau) = \begin{cases} 1, & x \in D_p, \\ 0, & x \in \mathbb{G} \setminus D_p. \end{cases}$$

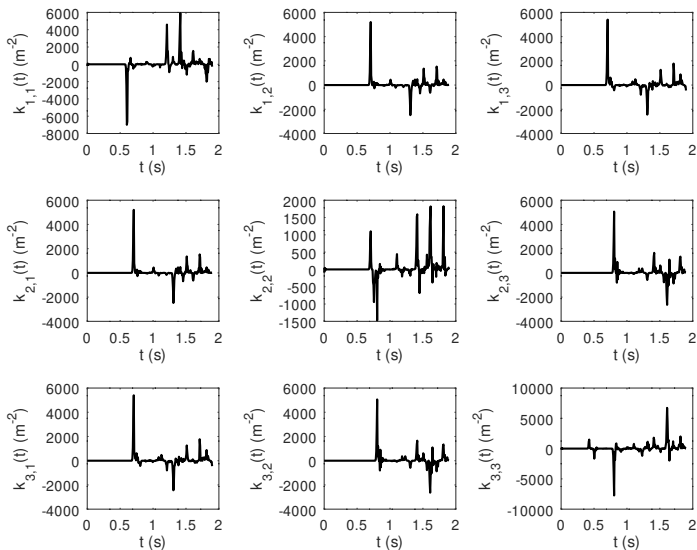


## Numerical experiment: setup

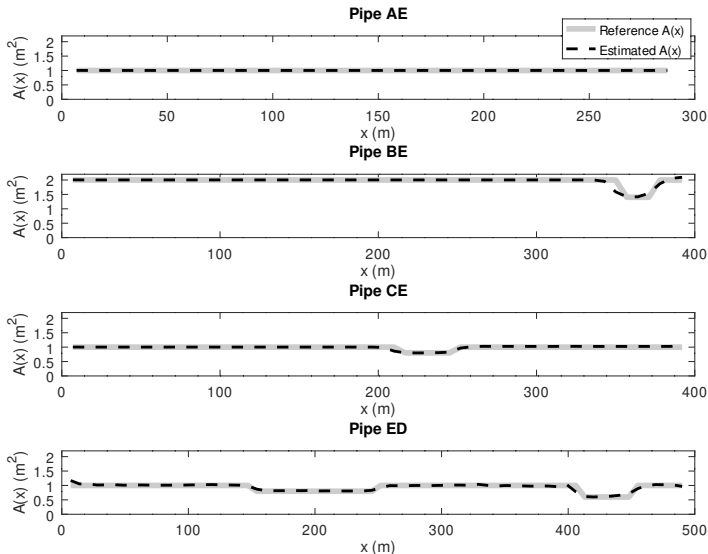


# Numerical experiment: impulse-response matrix function

$$h_{ij}(t) = A(x_j)g/a_0 \cdot k_{ij}(t)$$



# Reconstruction from measured data using regularization



## Existence of solution?

If

$$\tilde{Q}(x_j, t) = \begin{cases} \nu(x_j) Q_p(t, x_j), & 0 \leq t \leq \tau, \\ \nu(x_j) Q_p(2\tau - t, x_j), & \tau < t \leq 2\tau, \\ 0, & \text{otherwise,} \end{cases}$$

and

$$\tilde{1}(x_j, t) = \begin{cases} 1, & |t - \tau| < f(x_j), \\ 0, & |t - \tau| \geq f(x_j), \end{cases}$$

then the equations for  $Q_p$  can be written as an operator equation

$$\mathcal{K} \tilde{Q}(x_j, t) = \frac{gA(x_j)}{a_0} \tilde{1}(x_j, t).$$

# Functional analysis

$$\mathcal{K} \tilde{Q}(x_j, t) = \frac{gA(x_j)}{a_0} \tilde{1}(x_j, t), \quad \tilde{Q} \in L_0^2$$

where  $\mathcal{K} : L_0^2 \rightarrow L_0^2$  are defined by

$$L_0^2 = \left\{ \tilde{Q} \in L^2(\partial\mathbb{G} \setminus \{x_0\} \times \mathbb{R}) \mid \right. \\ \left. \tilde{Q}(x_j, t) = 0 \text{ if } |t - \tau| \geq f(x_j), \tilde{Q}(x_j, 2\tau - t) = \tilde{Q}(x_j, t) \right\}.$$

and

$$\mathcal{K} \tilde{Q}(x_j, t) = \tilde{Q}(x_j, t) \\ + \sum_{x_i \in \partial\mathbb{G} \setminus \mathbb{J}} \frac{\tilde{1}(x_j, t)}{2} \int_0^{2\tau} \tilde{Q}(x_i, s) h_{ij}(|t - s|) ds.$$

$\mathcal{K}$  is self-adjoint, Fredholm, pos. semidef. and  $gA\tilde{1}/a_0 \perp \ker \mathcal{K}!!$

Kiitos!